

Online Appendix

Version: 23 March 2026

F Extended Lag Model

F.1 Consumer problem in the extended model

The key results in this paper focus on a simple case of the “short memory habits” (SMH) model in which the effects of addictive characteristics persist for only one period. Here, I show that the results extend easily to a more general L -lag SMH model.

Defining $L \in \mathbb{N}$ to be the length of habit persistence, my model of interest becomes

$$\max_{\{\mathbf{x}_t, y_t\}_{t=1}^T} \sum_{t=1}^T \beta^{t-1} (u(\mathbf{z}_t^c, \mathbf{z}_t^a, \mathbf{z}_{t-1}^a, \dots, \mathbf{z}_{t-L}^a) + y_t) \quad \text{subject to} \quad \sum_{t=1}^T \boldsymbol{\rho}'_t \mathbf{x}_t + \sum_{t=1}^T \beta^{t-1} y_t = W, \quad \mathbf{z}_t = \mathbf{A} \mathbf{x}_t, \quad (26)$$

where $\boldsymbol{\rho}_t$ denotes the vector of present-value prices, $\beta = 1/(1 + \delta)$ where $\delta \in [0, \infty)$ is the consumer’s rate of time preference, and W is the present value of the consumer’s lifetime wealth.

With this extended lag dependency, I redefine the augmented vectors and matrices via:

$$\tilde{\mathbf{z}}_t := \begin{pmatrix} \mathbf{z}_t^c \\ \mathbf{z}_t^a \\ \mathbf{z}_{t-1}^a \\ \vdots \\ \mathbf{z}_{t-L}^a \end{pmatrix} \quad \tilde{\mathbf{x}}_t := \begin{pmatrix} \mathbf{x}_t \\ \mathbf{x}_{t-1} \\ \vdots \\ \mathbf{x}_{t-L} \end{pmatrix} \quad \tilde{\mathbf{A}} := \begin{pmatrix} \mathbf{A} & \mathbf{0}_{J \times K} & \cdots & \mathbf{0}_{J \times K} \\ \mathbf{0}_{J_2 \times K} & \mathbf{A}^a & \cdots & \mathbf{0}_{J_2 \times K} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0}_{J_2 \times K} & \mathbf{0}_{J_2 \times K} & \cdots & \mathbf{A}^a \end{pmatrix}, \quad (27)$$

so that $\tilde{\mathbf{z}}_t$ is now a $J + LJ_2$ column vector, $\tilde{\mathbf{x}}_t$ is a $(L + 1)K$ column vector, and $\tilde{\mathbf{A}}$ is a $(J + LJ_2) \times (L + 1)K$ block matrix. Using this augmented notation, the general L -lag model can be written as

$$\max_{\{\mathbf{x}_t, y_t\}_{t=1}^T} \sum_{t=1}^T \beta^{t-1} (u(\tilde{\mathbf{z}}_t) + y_t) \quad \text{subject to} \quad \sum_{t=1}^T \boldsymbol{\rho}'_t \mathbf{x}_t + \sum_{t=1}^T \beta^{t-1} y_t = W, \quad \tilde{\mathbf{z}}_t = \tilde{\mathbf{A}} \tilde{\mathbf{x}}_t. \quad (28)$$

Notice that by setting $L = 1$, I recover the basic model analysed in Section 2. By quasi-linearity, the outside good can be suppressed and the analysis can be conducted in terms of $\{\mathbf{x}_t\}$ and the present-value expenditure constraint; see Appendix A for details on this suppression step.

F.2 Consistency in the extended model

The Lagrangian for the constrained optimisation problem associated with the extended lag model is

$$\mathcal{L}(\{\mathbf{x}_t\}) = \sum_{t=1}^T \beta^{t-1} u(\tilde{\mathbf{A}} \tilde{\mathbf{x}}_t) - \left\{ \sum_{t=1}^T \boldsymbol{\rho}'_t \mathbf{x}_t - W \right\}, \quad (29)$$

where I normalise $\lambda = 1$ without loss of generality, quasi-linearity justifies suppressing the outside good and W is now interpreted as lifetime wealth net of outside-good consumption; see Appendix A for details.

The associated first-order necessary conditions follow as before using the chain rule, noting I now have the

following changes in dimensionality:

$$\underbrace{\frac{\partial u(\tilde{\mathbf{A}}\tilde{\mathbf{x}}_t)}{\partial \mathbf{x}_t}}_{(K \times 1)} = \underbrace{\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_t}}_{(K \times (L+1)K)} \underbrace{\frac{\partial u(\tilde{\mathbf{z}}_t)}{\partial \tilde{\mathbf{x}}_t}}_{((L+1)K \times 1)} = \underbrace{\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_t}}_{(K \times (L+1)K)} \underbrace{\frac{\partial \tilde{\mathbf{z}}_t}{\partial \tilde{\mathbf{x}}_t}}_{((L+1)K \times (J+LJ_2))} \underbrace{\frac{\partial u(\tilde{\mathbf{z}}_t)}{\partial \tilde{\mathbf{z}}_t}}_{((J+LJ_2) \times 1)} \quad (30)$$

where, using my notation defined in (27) I have,

$$\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_t} = \left[\mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times LK} \right],$$

$$\frac{\partial \tilde{\mathbf{z}}_t}{\partial \tilde{\mathbf{x}}_t} = \frac{\partial(\tilde{\mathbf{A}}\tilde{\mathbf{x}}_t)}{\partial \tilde{\mathbf{x}}_t} = \tilde{\mathbf{A}}',$$

$$\frac{\partial u(\tilde{\mathbf{z}}_t)}{\partial \tilde{\mathbf{z}}_t} = \partial u(\tilde{\mathbf{z}}_t) := \left[\partial_{z_t^c} u(\tilde{\mathbf{z}}_t)', \partial_{z_t^a} u(\tilde{\mathbf{z}}_t)', \partial_{z_{t-1}^a} u(\tilde{\mathbf{z}}_t)', \dots, \partial_{z_{t-L}^a} u(\tilde{\mathbf{z}}_t)' \right]',$$

where \mid denotes the horizontal concatenation of the $K \times K$ identity matrix and the $K \times LK$ matrix of zeros, and $\partial u(\tilde{\mathbf{z}})$ denotes the superderivative of u at $\tilde{\mathbf{z}}$. Repeating the chain rule exercise in (30), except this time differentiating with respect to the l -period lag of market goods, $l \in \{1, \dots, L\}$, I have,

$$\underbrace{\frac{\partial u(\tilde{\mathbf{A}}\tilde{\mathbf{x}}_t)}{\partial \mathbf{x}_{t-l}}}_{(K \times 1)} = \underbrace{\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_{t-l}}}_{(K \times (L+1)K)} \underbrace{\frac{\partial u(\tilde{\mathbf{z}}_t)}{\partial \tilde{\mathbf{x}}_t}}_{((L+1)K \times 1)} = \underbrace{\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_{t-l}}}_{(K \times (L+1)K)} \underbrace{\frac{\partial \tilde{\mathbf{z}}_t}{\partial \tilde{\mathbf{x}}_t}}_{((L+1)K \times (J+LJ_2))} \underbrace{\frac{\partial u(\tilde{\mathbf{z}}_t)}{\partial \tilde{\mathbf{z}}_t}}_{((J+LJ_2) \times 1)} \quad (31)$$

where the only new term is,

$$\frac{\partial \tilde{\mathbf{x}}_t}{\partial \mathbf{x}_{t-l}} = \left[\mathbf{0}_{K \times lK} \mid \mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times (L-l)K} \right].$$

It follows from these intermediate calculations of the vector derivatives that,

$$\frac{\partial u(\tilde{\mathbf{A}}\tilde{\mathbf{x}}_t)}{\partial \mathbf{x}_t} = \left[\mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times LK} \right] \tilde{\mathbf{A}}' \partial u(\tilde{\mathbf{z}}_t)$$

and for all $l \in \{1, \dots, L\}$,

$$\frac{\partial u(\tilde{\mathbf{A}}\tilde{\mathbf{x}}_{t+l})}{\partial \mathbf{x}_t} = \left[\mathbf{0}_{K \times lK} \mid \mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times (L-l)K} \right] \tilde{\mathbf{A}}' \partial u(\tilde{\mathbf{z}}_{t+l}).$$

The first-order necessary conditions associated with the Lagrangian in (29) now follow immediately as,

$$\partial_{\mathbf{x}_t} \mathcal{L} = 0 \quad \Rightarrow \quad \boldsymbol{\rho}_t = \beta^{t-1} \left(\left[\mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times LK} \right] \tilde{\mathbf{A}}' \partial u(\tilde{\mathbf{z}}_t) + \sum_{l=1}^L \beta^l \left[\mathbf{0}_{K \times lK} \mid \mathbf{I}_{K \times K} \mid \mathbf{0}_{K \times (L-l)K} \right] \tilde{\mathbf{A}}' \partial u(\tilde{\mathbf{z}}_{t+l}) \right). \quad (32)$$

But, just as in the simple case of $L = 1$, these first-order conditions can be substantially simplified. Multiplying

the conformable block matrices as in Section 2 the first-order conditions in (32) reduce to:

$$\boldsymbol{\rho}_t = \beta^{t-1} \left(\mathbf{A}' \begin{bmatrix} \partial_{\mathbf{z}_t^c} u(\tilde{\mathbf{z}}_t) \\ \partial_{\mathbf{z}_t^a} u(\tilde{\mathbf{z}}_t) \end{bmatrix} + \sum_{l=1}^L \beta^l (\mathbf{A}^a)' \begin{bmatrix} \partial_{\mathbf{z}_t^c} u(\tilde{\mathbf{z}}_{t+l}) \\ \partial_{\mathbf{z}_t^a} u(\tilde{\mathbf{z}}_{t+l}) \end{bmatrix} \right). \quad (33)$$

This gives rise to my formal definition of *consistency* in the extended SMH model as follows:

Definition F.1. The data $\{\boldsymbol{\rho}_t; \mathbf{x}_t\}_{t \in \{1, \dots, T\}}$ are *consistent* with the L -lag habits-over-characteristics model for given technology \mathbf{A} if they solve the agent's lifetime utility maximisation problem defined in Equation (28), for some locally non-satiated, superdifferentiable, and concave utility function $u(\cdot)$ and discount factor $\beta \in (0, 1]$.

The following lemma provides a set of necessary and sufficient conditions for this extended lag form of consistency to hold.

Lemma F.1. The data $\{\boldsymbol{\rho}_t; \mathbf{x}_t\}_{t \in \{1, \dots, T\}}$ are *consistent* with the L -lag habits-over-characteristics model for given technology \mathbf{A} if there exists a locally non-satiated, superdifferentiable, and concave utility function $u(\cdot)$ and discount factor $\beta \in (0, 1]$ such that for all $t \in \{1, \dots, T - L\}$,

$$\boldsymbol{\rho}_t \geq \mathbf{A}' \boldsymbol{\pi}_t^0 + \sum_{l=1}^L (\mathbf{A}^a)' \boldsymbol{\pi}_{t+l}^l, \quad (\star L)$$

with equality for all k such that $x_t^k > 0$, and where discounted shadow prices are defined as:

$$\boldsymbol{\pi}_t^0 = \beta^{t-1} \begin{bmatrix} \partial_{\mathbf{z}_t^c} u(\tilde{\mathbf{z}}_t) \\ \partial_{\mathbf{z}_t^a} u(\tilde{\mathbf{z}}_t) \end{bmatrix}, \quad (SP_0)$$

$$\boldsymbol{\pi}_t^l = \beta^{t-1} \begin{bmatrix} \partial_{\mathbf{z}_{t-l}^c} u(\tilde{\mathbf{z}}_t) \\ \partial_{\mathbf{z}_{t-l}^a} u(\tilde{\mathbf{z}}_t) \end{bmatrix}, \quad (SP_l)$$

where $\tilde{\mathbf{z}}_t = \tilde{\mathbf{A}} \tilde{\mathbf{x}}_t$ for all $t \in \{1, \dots, T\}$, and $\boldsymbol{\rho}_t$ denotes the vector of present-value prices.

I can interpret $\boldsymbol{\pi}_t^l$ as the discounted WTP for the consumption of habit-forming characteristics l periods ago.

Clearly, Definition F.1 and Lemma F.1 nest the simple one-lag habits-over-characteristics model when $L = 1$. Indeed, the latter gives the natural (dynamic) extension of the hedonic pricing equation when habits persist for exactly L periods. It tells us that the discounted prices $\boldsymbol{\rho}_t$ of goods today depend on current discounted shadow prices of the characteristics *as well as* the discounted shadow price of habit-forming characteristics tomorrow, $\boldsymbol{\pi}_{t+1}^1$, the next day, $\boldsymbol{\pi}_{t+2}^2$, and up to L periods in the future, $\boldsymbol{\pi}_{t+3}^3, \dots, \boldsymbol{\pi}_{t+L}^L$. This is because today's consumption of goods (and the habit-forming characteristics contained therein) affects the agent's marginal utility L periods in the future by building up a habit. A characterisation of this notion of consistency in the extended SMH model follows naturally from Theorem 2.1.

F.3 Afriat conditions in the extended model

Theorem F.1. The following statements are equivalent:

(A_L) The data $\{\boldsymbol{\rho}_t; \mathbf{x}_t\}_{t \in \{1, \dots, T\}}$ are consistent with the L -lag habits model for given technology \mathbf{A} .

(B_L) There exist T J -vector shadow discounted prices $\{\boldsymbol{\pi}_t^0\}_{t \in \{1, \dots, T\}}$, T LJ_2 -vector shadow discounted prices $\{\boldsymbol{\pi}_t^1, \dots, \boldsymbol{\pi}_t^L\}_{t \in \{1, \dots, T\}}$ and discount factor $\beta \in (0, 1]$ such that,

$$0 \leq \sum_{\forall s, t \in \sigma} \tilde{\boldsymbol{\pi}}_s' (\tilde{\mathbf{z}}_t - \tilde{\mathbf{z}}_s) \quad \forall \sigma \subseteq \{1, \dots, T\} \quad (B1_L)$$

$$\rho_t^k \geq \mathbf{a}'_k \boldsymbol{\pi}_t^0 + \sum_{l=1}^L \mathbf{a}^{al}_k \boldsymbol{\pi}_{t+l}^l \quad \forall k, t \in \{1, \dots, T-L\} \quad (B2_L)$$

$$\rho_t^k = \mathbf{a}'_k \boldsymbol{\pi}_t^0 + \sum_{l=1}^L \mathbf{a}^{al}_k \boldsymbol{\pi}_{t+l}^l \quad \text{if } x_t^k > 0, \forall k, t \in \{1, \dots, T-L\} \quad (B3_L)$$

where \mathbf{a}_k is the J -vector corresponding to the k -th column of \mathbf{A} , \mathbf{a}_k^a is the J_2 -vector corresponding to the last J_2 rows of the k -th column of \mathbf{A} , and $\tilde{\boldsymbol{\pi}}_t := \frac{1}{\beta^{t-1}} [\boldsymbol{\pi}_t^{0'}, \boldsymbol{\pi}_t^{1'}, \dots, \boldsymbol{\pi}_t^{L'}]'$.

Proof. Identical to Theorem 2.1 with extended lag notation. \square

G Testing model consistency via linear programming

Theorem 2.1 defines the conditions for theoretical consistency of the data. As discussed in Section 2.2, theoretical consistency of the data reduces to a linear programming problem when one commits to a grid search over the discount factor, β . However, in its current form, condition (B) is inconvenient for practical implementation because (B1) requires checking cyclical monotonicity over all finite ordered cycles of observations. To address this issue, I derive the following equivalent statement to be used when implementing the test for model consistency.

Theorem G.1. The following statements are equivalent:

- (A) The data $\{\rho_t; \mathbf{x}_t\}_{t \in \{1, \dots, T\}}$ are consistent with the one-lag habits-over-characteristics model for given technology \mathbf{A} .
- (L) There exist T numbers $\{V_t\}_{t=1, \dots, T}$, T J -vector shadow discounted prices $\{\pi_t^0\}_{t \in \{1, \dots, T\}}$, T J_2 -vector shadow discounted prices $\{\pi_t^1\}_{t \in \{1, \dots, T\}}$ and a positive constant β such that,

$$V_s - V_t - \frac{1}{\beta^{t-1}} \left[\pi_t^{0'}, \pi_t^{1'} \right] (\tilde{\mathbf{z}}_s - \tilde{\mathbf{z}}_t) \leq 0 \quad \forall s, t \in \{1, \dots, T\} \quad (\text{L1})$$

$$\left[\mathbf{A}' \mid (\mathbf{A}^a)' \right] \begin{bmatrix} \pi_t^0 \\ \pi_{t+1}^1 \end{bmatrix} \leq \rho_t \quad \forall t \in \{1, \dots, T-1\} \quad (\text{L2})$$

$$\left[\mathbf{B}_t' \mid (\mathbf{B}_t^a)' \right] \begin{bmatrix} \pi_t^0 \\ \pi_{t+1}^1 \end{bmatrix} = \rho_t^+ \quad \forall t \in \{1, \dots, T-1\} \quad (\text{L3})$$

where ρ_t^+ is a K_t^+ vector equal to the sub-vector of period t prices for which demands are positive, and \mathbf{B}_t and \mathbf{B}_t^a are the corresponding $J \times K_t^+$ and $J_2 \times K_t^+$ sub-matrices matrices of \mathbf{A} and \mathbf{A}^a , respectively (as introduced in Section 2.4).

Notice that the original (B1) has been converted to the equivalent constraint (L1), which requires testing only a quadratic number of pairwise inequalities in T .

Proof.

Condition (A) is identical to that in Theorem 2.1. Accounting for notational differences, conditions (L2) and (L3) are also identical to conditions (B2) and (B3) in Theorem 2.1, respectively. Hence, the proof reduces to showing that condition (L1) is equivalent to condition (B1) in Theorem 2.1.

(B1) \Rightarrow (L1): Assume (B1) holds. Then the finite dataset $\{(\tilde{\mathbf{z}}_t, \tilde{\pi}_t)\}_{t=1}^T$ is cyclically monotone in the sense of Browning (1989). By the standard finite-sample Afriat inequalities (Afriat, 1967; Diewert, 1973; Varian, 1982), cyclical monotonicity is equivalent to the existence of T numbers $\{V_t\}_{t=1}^T$ such that

$$V_s \leq V_t + \tilde{\pi}_t' (\tilde{\mathbf{z}}_s - \tilde{\mathbf{z}}_t) \quad \forall s, t \in \{1, \dots, T\}.$$

Rearranging yields

$$0 \leq V_t - V_s + \tilde{\pi}_t' (\tilde{\mathbf{z}}_s - \tilde{\mathbf{z}}_t), \quad \forall s, t \in \{1, \dots, T\}.$$

Substituting in the definition for $\tilde{\pi}_t$ from Theorem 2.1 gives,

$$V_s - V_t - \frac{1}{\beta^{t-1}} \left[\pi_t^{0'}, \pi_t^{1'} \right] (\tilde{z}_s - \tilde{z}_t) \leq 0 \quad \forall s, t \in \{1, \dots, T\},$$

which is constraint (L1).

(L1) \Rightarrow (B1): Assume (L1) holds. Using the augmented notation, this means that

$$0 \leq V_t - V_s + \tilde{\pi}'_t (\tilde{z}_s - \tilde{z}_t), \quad \forall s, t \in \{1, \dots, T\}.$$

Take any finite ordered cycle (t_1, \dots, t_M) with $t_{M+1} = t_1$. Summing the corresponding inequalities from (L1) over $m = 1, \dots, M$ makes the Afriat numbers telescope, yielding

$$0 \leq \sum_{m=1}^M \tilde{\pi}'_{t_m} (\tilde{z}_{t_{m+1}} - \tilde{z}_{t_m}),$$

which is condition (B1). \square